

UNIVERSITY

LEVEL's Degree in COURSE



LEVEL's Degree Thesis

TITLE

Supervisors

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Candidate

NAME SURNAME

MONTH YEAR

Summary

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Acknowledgements

ACKNOWLEDGMENTS

*“HI”
Goofy, Google by Google*

Table of Contents

List of Tables	VI
List of Figures	VII
Acronyms	IX
1 Hello	1
1.1 Extremely long name with manual linebreak which otherwise would not fit the page	1
A Galileo	5
Bibliography	6

List of Tables

1.1	Examples of activation functions, operating either element-wise or vector-wise, depending on the function	2
1.2	y is the output of the network, N is the batch size multiplied by the number of outputs (e.g. pixels), C is the number of classes and \hat{y} is the correct output.	4

List of Figures

1.1	Hi	1
1.2	HI	2
1.3	SVG	2

Acronyms

AI

artificial intelligence

Chapter 1

Hello

[Hi 1, Goofy]
kg s⁻¹



Figure 1.1: Hi

1.1 Extremely long name with manual linebreak which otherwise would not fit the page

1. A
2. B
3. C



**POLITECNICO
DI TORINO**

Figure 1.2: HI

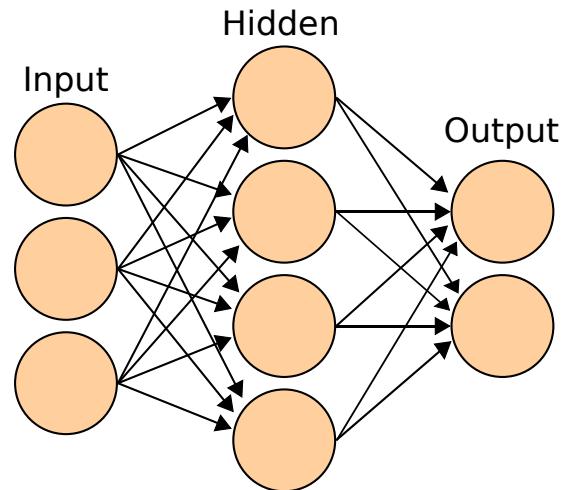


Figure 1.3: SVG

ReLU	$f(x) = \begin{cases} 0 & \text{for } x \leq 0 \\ x & \text{for } x > 0 \end{cases}$
Softmax	$f_i(\vec{x}) = \frac{e^{x_i}}{\sum_{j=1}^J e^{x_j}} i = 1, \dots, J$
tanh	$f(x) = \tanh(x) = \frac{(e^x - e^{-x})}{(e^x + e^{-x})}$

Table 1.1: Examples of activation functions, operating either element-wise or vector-wise, depending on the function

$$\text{output} = f_{activation} \left(\sum_{\#neurons} \text{input}_i + \text{bias} \right) \quad (1.1)$$

- A
- B
- C

Algorithm 1 Adam optimizer algorithm. All operations are element-wise, even powers. Good values for the constants are $\alpha = 0.001$, $\beta_1 = 0.9$, $\beta_2 = 0.999$, $\epsilon = 10^{-8}$. ϵ is needed to guarantee numerical stability.

```
1: procedure ADAM( $\alpha, \beta_1, \beta_2, f, \theta_0$ )
2:    $\triangleright \alpha$  is the stepsize
3:    $\triangleright \beta_1, \beta_2 \in [0, 1]$  are the exponential decay rates for the moment estimates
4:    $\triangleright f(\theta)$  is the objective function to optimize
5:    $\triangleright \theta_0$  is the initial vector of parameters which will be optimized
6:    $\triangleright$  Initialization
7:    $m_0 \leftarrow 0$   $\triangleright$  First moment estimate vector set to 0
8:    $v_0 \leftarrow 0$   $\triangleright$  Second moment estimate vector set to 0
9:    $t \leftarrow 0$   $\triangleright$  Timestep set to 0
10:   $\triangleright$  Execution
11:  while  $\theta_t$  not converged do
12:     $t \leftarrow t + 1$   $\triangleright$  Update timestep
13:     $\triangleright$  Gradients are computed w.r.t the parameters to optimize
14:     $\triangleright$  using the value of the objective function
15:     $\triangleright$  at the previous timestep
16:     $g_t \leftarrow \nabla_{\theta} f(\theta_{t-1})$ 
17:     $\triangleright$  Update of first-moment and second-moment estimates using
18:     $\triangleright$  previous value and new gradients, biased
19:     $m_t \leftarrow \beta_1 \cdot m_{t-1} + (1 - \beta_1) \cdot g_t$ 
20:     $v_t \leftarrow \beta_2 \cdot v_{t-1} + (1 - \beta_2) \cdot g_t^2$ 
21:     $\triangleright$  Bias-correction of estimates
22:     $\hat{m}_t \leftarrow \frac{m_t}{1 - \beta_1^t}$ 
23:     $\hat{v}_t \leftarrow \frac{v_t}{1 - \beta_2^t}$ 
24:     $\theta_t \leftarrow \theta_{t-1} - \alpha \cdot \frac{\hat{m}_t}{\sqrt{\hat{v}_t} + \epsilon}$   $\triangleright$  Update parameters
25:  end while
26:  return  $\theta_t$   $\triangleright$  Optimized parameters are returned
27: end procedure
```

MSE / L2 Loss / Quadratic Loss	$\frac{\sum_{i=1}^N (y_i - \hat{y}_i)^2}{N}$
(Binary) Cross Entropy (average reduction on higher dimensions)	$\frac{\sum_{i=1}^N \sum_{j=1}^C \hat{y}_i \log (y_{i,j})}{N}$
Categorical Cross Entropy (sum reduction on higher dimensions)	$-\sum_{i=1}^N \hat{y}_i + \log \left(\sum_{i=1}^N \sum_{j=1}^C y_{i,j} \right)$

Table 1.2: y is the output of the network, N is the batch size multiplied by the number of outputs (e.g. pixels), C is the number of classes and \hat{y} is the correct output.

Appendix A

Galileo

```
1 import os  
2 os.system("echo 1")
```

$\mathcal{O}(n \log n)$
numpy

Bibliography

- [1] S. Zhang, C. Zhu, J. K. O. Sin, and P. K. T. Mok. «A Novel Ultrathin Elevated Channel Low-temperature Poly-Si TFT». In: 20 (Nov. 1999), pp. 569–571 (cit. on p. 1).